CSCE 658: Randomized Algorithms

Lecture 11

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Class Logistics

• March 5: Lecture canceled, i.e., do NOT show up to HRBB 126 (unless you want to see an empty classroom)

Previously in the Streaming Model

- Reservoir sampling
- Heavy-hitters
 - Misra-Gries
 - CountMin
 - CountSketch
- Moment estimation
 - AMS algorithm
- Sparse recovery
- Distinct elements estimation

Reservoir Sampling

• Suppose we see a stream of elements from [*n*]. How do we uniformly sample one of the positions of the stream?

47 72 81 10 14 33 51 29 54 9 36 46 10

Heavy-Hitters (Frequent Items)

- Given a set *S* of *m* elements from [n], let f_i be the frequency of element *i*. (How often it appears)
- Let L_p be the norm of the frequency vector:

$$L_{p} = \left(f_{1}^{p} + f_{2}^{p} + \dots + f_{n}^{p}\right)^{1/p}$$

- Goal: Given a set S of m elements from [n] and a threshold ε , output the elements i such that $f_i > \varepsilon L_p$...and no elements j such that $f_j < \frac{\varepsilon}{2} L_p$ (we saw algorithms for p = 1 and p = 2)
- Motivation: DDoS prevention, iceberg queries

Frequency Moments (L_p Norm)

- Given a set *S* of *m* elements from [n], let f_i be the frequency of element *i*. (How often it appears)
- Let F_p be the frequency moment of the vector:

$$F_p = f_1^p + f_2^p + \dots + f_n^p$$

- Goal: Given a set *S* of *m* elements from [n] and an accuracy parameter ε , output a $(1 + \varepsilon)$ -approximation to F_p
- Motivation: Entropy estimation, linear regression

The Streaming Model

• So far, all questions have been *statistical*

• What other questions can be asked? (Think in general, outside of the streaming model)

The Streaming Model

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- What other questions can be asked? (Think in general, outside of the streaming model)
- Algebraic, geometric

The Streaming Model

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• What other questions can be asked? (Think in general, outside of the streaming model)



Graph Theory

• Suppose we have a graph G with vertex set V and edge set E

• Let V = [n] for simplicity, so each vertex is an integer from 1 to n

- Then each edge $e \in E$ can be written as e = (u, v) for $u, v \in [n]$
- In other words, each edge is a pair of integers from 1 to n

Graph Theory

• For today, we will assume a simple, undirected, unweighted graph

- Graph has no self-loops, no multi-edges
- Edges are undirected
- Each edge has weight 1

Semi-streaming Model

- Recall that we have a graph G = (V = [n], E)
- Suppose |E| = m
- The edges of the graph arrive sequentially, i.e., insertion-only model
- We are allowed to use $n \cdot \text{polylog}(n)$ space
- Enough to store things like a matching, a spanning tree, NOT enough to store entire graph, since m can be as large as $O(n^2)$



• Bipartite graph: Graph can be partitioned into two disjoint sets L and R so that every edge is between a vertex in L and a vertex in R

• Goal: Given a graph G, determine whether G is a bipartite graph









Applications for Bipartiteness Testing

• Graph coloring: You want to color a graph such that no neighboring items share the same color





Applications for Bipartiteness Testing

 Circuit design: In electrical engineering and VLSI (Very Large Scale Integration) design, you may want to know if a circuit can be optimally partitioned into two complementary parts, which can be achieved by testing the bipartiteness of the circuit's dependency graph



• What is a necessary and sufficient condition for bipartiteness?

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• A graph is bipartite if and only if it can be colored using two colors (a coloring of a graph is an assignment of colors to vertices such that no two vertices share the same color)

• A graph is bipartite if and only if it has no odd cycles

• How to perform bipartiteness testing in the central setting?

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• Start at arbitrary vertex, run BFS, and assign alternating levels to different side until there is a contradiction









• Bipartiteness is a monotone property, i.e., additional edges to a graph that is not bipartite will result in a graph that is not bipartite

- Intuition: Greedily add edges to minimum spanning forest
- Algorithm:
 - 1. Initialize $F = \emptyset$.
 - 2. For each edge e = (u, v):
 - 1. If $F \cup (u, v)$ does not contain a cycle, add (u, v) to $F: F \leftarrow F \cup (u, v)$
 - 2. If $F \cup (u, v)$ contains an odd cycle, return GRAPH IS NOT BIPARTITE
 - 3. Return GRAPH IS BIPARTITE

 Algorithm maintains a tree (because it does not add any edges that would create cycles)

• How many edges does the algorithm keep?

 Algorithm maintains a tree (because it does not add any edges that would create cycles)

Algorithm can keep at most n edges, so the total space usage is
 O(n) words of space.



• Goal: Given input dataset X, partition X so that "similar" points are in the same cluster and "different" points are in different clusters



- Goal: Given input dataset X, partition X so that "similar" points are in the same cluster and "different" points are in different clusters
- There can be at most *k* different clusters



• Question: How do we measure the "quality" of each clustering?



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- Assign a "center" *c*_{*i*} to each cluster
- Have a cost function induced by c_i for all of the points P_i assigned to cluster i

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- Assign a "center" *c*_{*i*} to each cluster
- Have a cost function induced by c_i for all of the points P_i assigned to cluster i
 - Assume points are in metric space with distance function dist(·,·)
 - Define $Cost(P_i, c_i)$ to be a function of $\{dist(x, c_i)\}_{x \in P_i}$

- Question: How do we measure the "quality" of each clustering?
- Have a cost function induced by c_i for all of the points P_i assigned to cluster i
 - Define $Cost(P_i, c_i)$ to be a function of $\{dist(x, c_i)\}_{x \in P_i}$
- Suppose the set of centers is $C = \{c_1, \dots, c_k\}$
 - Define clustering cost Cost(X, C) to be a function of {dist(x, C)}_{x∈C}

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• *k*-center: $Cost(X, C) = \max_{x \in X} dist(x, C)$

- Define clustering cost Cost(X, C) to be a function of ${\operatorname{dist}(x,C)}_{x \in X}$
- k-center: $Cost(X, C) = \max_{x \in X} dist(x, C)$ k-median: $Cost(X, C) = \sum_{x \in X} dist(x, C)$



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- k-center: $Cost(X, C) = \max_{x \in X} dist(x, C)$ k-median: $Cost(X, C) = \sum_{x \in X} dist(x, C)$
- k-means: $\operatorname{Cost}(X, C) = \sum_{x \in X} (\operatorname{dist}(x, C))^2$



 Define clustering cost Cost(X, C) to be a function of {dist(x, C)}_{x∈X}

(·)^z

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- k-center: $Cost(X, C) = \max_{x \in X} dist(x, C)$
- *k*-median: $Cost(X, C) = \sum_{x \in X}^{X \in A} dist(x, C)$
- *k*-means: $\operatorname{Cost}(X, C) = \sum_{x \in X} (\operatorname{dist}(x, C))^2$
- (k, z)-clustering: $Cost(X, C) = \sum_{x \in X} (dist(x, C))^{z}$

Euclidean k-Clustering

• For Euclidean k-clustering, input points $X = x_1, ..., x_n$ are in \mathbb{R}^d (for us, they will be in $[\Delta]^d \coloneqq \{1, 2, ..., \Delta\}^d$)

• dist $(x, y) = \sqrt{(x_1 - y_1)^2 + \dots + (x_d - y_d)^2}$ is the Euclidean distance

• (*k*, *z*)-clustering problem:

$$\min_{C:|C|\leq k} \operatorname{Cost}(X,C) = \min_{C:|C|\leq k} \sum_{x\in X} \left(\operatorname{dist}(x,C)\right)^{z}$$

$$\begin{array}{c}
\circ (-8,4) \\
(-4,3) \\
\circ \\
(-3,0) \\
\circ \\
(-11,-4) \\
(0,-4)
\end{array}$$
(4,3)
(4,3)
(4,3)
(0,-4)







k-median: $Cost(X, C) = \sum_{x \in X} dist(x, C) = 4 + 5 + 5 + 3 + 4 + 5 = 26$



k-means: $\operatorname{Cost}(X, C) = \sum_{x \in X} (\operatorname{dist}(x, C))^2 = 16 + 25 + 25 + 9 + 16 + 25$ o^(-8,4) = 116 (4, 3)(-4,3) 4 5 5 3 -8,0)(0, 0)(-3, 0)5 4 -4) (0, -4)

Coreset

- Subset X' of representative points of X for a specific clustering objective
- $Cost(X, C) \approx Cost(X', C)$ for all sets C with |C| = k

Coreset

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• $Cost(X, C) \approx Cost(X', C)$ for all sets C with |C| = k

Coreset

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Coreset (Formal Definition)

• Given a set X and an accuracy parameter $\varepsilon > 0$, we say a set X' with weight function w is an $(1 + \varepsilon)$ -multiplicative coreset for a cost function Cost, if for all queries C with $|C| \le k$, we have

 $(1 - \varepsilon)\operatorname{Cost}(X, C) \leq \operatorname{Cost}(X', C, w) \leq (1 + \varepsilon)\operatorname{Cost}(X, C)$ $(k, z) \text{-clustering: } \operatorname{Cost}(X', C, w) = \sum_{x \in X'} w(x) \cdot \left(\operatorname{dist}(x, C)\right)^{z}$

• Merge-and-reduce framework

• Suppose there exists a $(1 + \varepsilon)$ -coreset construction for (k, z)-clustering that uses $f\left(k, \frac{1}{\varepsilon}\right)$ weighted input points $\int \tilde{o}\left(\frac{k^2}{\varepsilon^2}\right)$ • Partition the stream into blocks containing $f\left(k, \frac{\log n}{\varepsilon}\right)$ points

• Partition the stream into blocks containing $f\left(k, \frac{\log n}{c}\right)$ points

• Create a $\left(1 + \frac{\varepsilon}{\log n}\right)$ -coreset for each block • Create a $\left(1 + \frac{\varepsilon}{\log n}\right)$ -coreset for the set of points formed by the union of two coresets for each block Reduce

- Partition the stream into blocks containing $f\left(k, \frac{\log n}{c}\right)$ points
- Create a $\left(1 + \frac{\varepsilon}{\log n}\right)$ -coreset for each block
- Create a $\left(1 + \frac{\varepsilon}{\log n}\right)$ -coreset for the set of points formed by the union of two coresets for each block



- There are $O(\log n)$ levels
- Each coreset is a $\left(1 + \frac{\varepsilon}{\log n}\right)$ -coreset of two coresets
- Total approximation is $\left(1 + \frac{\varepsilon}{\log n}\right)^{\log n} = (1 + O(\varepsilon))$



- Suppose there exists a $(1 + \varepsilon)$ -coreset construction for (k, z)-clustering that uses $f(k, \frac{1}{\varepsilon})$ weighted input points
- Partition the stream into blocks containing $f\left(k, \frac{\log n}{c}\right)$ points
- Total space is $f\left(k, \frac{\log n}{\epsilon}\right) \cdot O(\log n)$ points

For k-means clustering, this is $\tilde{O}\left(\frac{k^2}{\epsilon^2} \cdot \log^3 n\right)$ points