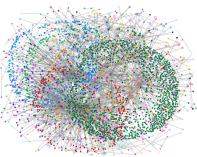
Sublinear Time Algorithms

Motivation

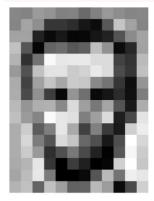
- \triangleright Algorithm takes input of size *n*
 - Pixels of an image
 - ▷ Entries in an adjacency matrix of a graph.
- \triangleright *n* is large
- Assumed to be too slow to look at entire input





Pixels of an Image

Input size n is the number of pixels

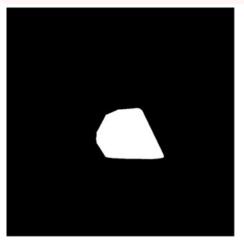


157	153	174	168	150	162	129	151	172	161	155	156
155	182	163						110	210	180	154
180	180			34			33	48	105	169	181
206	109		124	191	111	120	204	166			180
194		197	251	237	239	239	228	227			201
172	105	207	233	233	214	220	239	228	95		206
188		179	209	185	215	211	158	139		20	169
189	97	165	84		168	134		31			148
199	168	191	193	158	227	178	143	182	105	36	190
205	174	155	252	236	231	149	178	228			234
190	216	116	149	236	187		150		38	218	241
190	224	147	108	227	210	127	102		101	255	224
190	214	173	66	103	143	95	50		109	249	215
187	196	235							217	255	211
183	202	237	145				108	200	138	243	296
195	206	123	207	177	121	123	200	175	13	96	218

157	153	174	168	150	152	129	151	172	161	155	156
195	182	163	74	75	62	33	17	110	210	180	154
180	180	50	14	34	6	10	33	48	106	159	181
206	109	5	124	131	111	120	204	166	15	56	180
194	68	137	251	237	239	239	228	227	87	n	201
172	105	207	233	233	214	220	239	228	98	74	206
188	88	179	209	185	215	211	158	139	75	20	169
189	97	165	84	10	168	134	11	31	62	22	148
199	168	191	193	158	227	178	143	182	106	36	190
206	174	195	252	236	231	149	178	228	43	95	234
190	216	116	149	236	187	86	150	79	38	218	241
190	224	147	108	227	210	127	102	36	101	255	224
190	214	173	66	103	143	96	50	2	109	249	215
187	196	235	75	1	81	47	0	6	217	255	211
183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

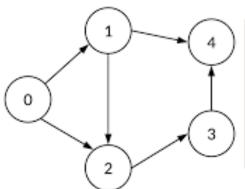
Example Problem on Image

Is the image a convex shape?



Graph Adjacency Matrix

Input size n is the number of matrix entries

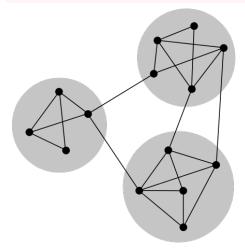


Adjacency Matrix

	0	1	2	3	4
0	0	1	1	0	0
1	0	0	1	0	1
2	0	0	0	1	0
3	0	0	0	0	1
4	0	0	0	0	0

Example Problem on Graph

Is the graph connected?



Sublinear Time Algorithm

Definition

A sublinear time algorithm is an algorithm whose execution time, T(n), grows slower than the size of the problem, n, but only gives an approximate or probably correct answer. So T(n) = o(n).

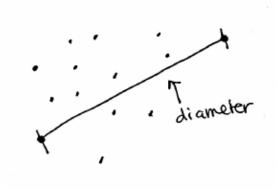
Examples of sublinear time:

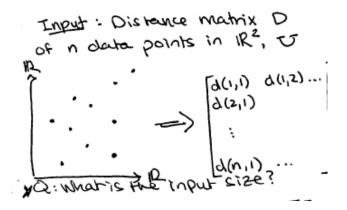
- $\triangleright O(\log(n))$
- $\triangleright \ {\it O}(1/\epsilon)$ for constant ϵ
- $\triangleright O(\sqrt{n})$

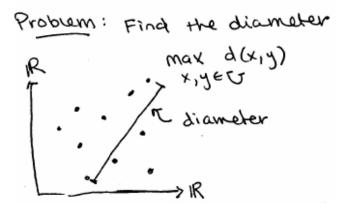
Sublinear Time Algorithms

- ▷ Can't answer "exactly" types of statements.
- Approximate answers
- ▷ Random samples

In this problem we wish to find the largest distance between any pair of points in a finite subset of \mathbb{R}^2 .

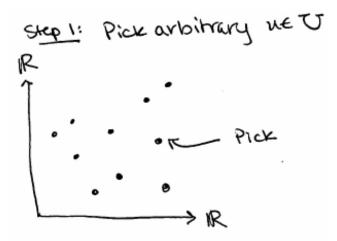




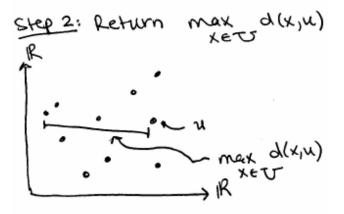


- ▷ Input is of size n^2
- $\,\triangleright\,$ Looking at each distance and finding max is linear time
- Instead propose algorithm that gives approximation

Algorithm for Diameter of a Metric Space



Algorithm for Diameter of a Metric Space



What is the run time of this algorithm?

.

What is the run time?
Input cize =
$$n^2$$

Run time = $a O(n)$
Algorithm is sublinear!

PF. Let
$$u',v'$$
 be the elements
of ∇r such that
 $d(u',v') = \max d(x,y)$. Then
 $x,y \in U$
the Δ property states that
 $d(u',v') \in d(u',u) + d(u,v')$
 $\leq 2 \max d(x,u)$. B

We now look at the problem of testing whether a binary string is all "0"s.

Algorithm we will take a random sampling approach.

Input: string we goilgn suppose that e fraction of the ware "1"s. So bigger E => mare "1's smaller E => Less "1"s E we uniformly vandanily sample a spot in w, what is the probability its a "0"?

Probability of sampling a"0" is 1-E. Took suppose we take s independent, unitermly random samples. * Probability of getting all 'O'!?

Nitnecs Lemma
If a test catches a witness
with probability
$$\geq e$$
, then
 $S = \frac{ln(F-p)}{e}$ iterations of the
test catches a witness with
probability $\geq p$.

$$\frac{Pf.}{P[don't catch witness]} \leq (1-\epsilon)^{S}$$

$$\leq e^{-\epsilon s} (zdentify 1 - x \leq e^{-x})$$

$$= e^{-\ln(f-p)} = \ln(1-p)$$

$$= e^{-1-p} = e^{-1-p}$$

$$\therefore P[catch witness] \geq p. \mathbb{R}$$

Algorithm tor approximate
all "O" tester
step 1: Take S=
$$\frac{ln(t-p)}{E}$$

random samples from
string w.
step 2: If all "O"=> return "YES
Otherwise => return "NO".

Approximate Algorithm for All "0" String

Suppose that $\epsilon = 0.2$ and p = 0.9999.

▷ What is s?

- Why does it not depend on the input size n?
- > What will the algorithm do on input:

 - "1001110001000111100111000111011001011001"

Input x is ϵ -far from property P if ϵ fraction of x has to be changed in order for x to have property P. E.g. P is whether x is an all "0" string.

What is the ϵ for the below input for the property of being all "0"?

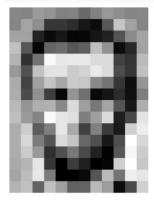
- "010000000"
- "0000000000"
- "0010101101"
- ⊳ "1111111111"

An algorithm with parameters $\epsilon, p \in (0.1)$, is an ϵ -tester of property *P* if:

- \triangleright If input x has property P it returns "YES" with probability at least p
- ▷ If input x is ϵ -far from property P it returns "NO" with probability at least p.

Pixels of an Image

Input size n is the number of pixels

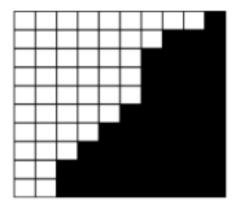


157	153	174	168	150	152	129	151	172	161	155	156
155	182	163						110	210	180	154
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189	97	165	84		168	134	11	31			148
199	168	191	193	158	227	178	143	182	105	36	190
205	174	155	252	236	231	149	178	228			234
190	216	116	149	236	187	85	150		38	218	241
190	224	147	108	227	210	127	102		101	255	224
190	214	173	66	103	143	95	50		109	249	215
187	196	235							217	255	211
183	202	237	145				108	200	138	243	296
195	206	123	207	177	121	123	200	175	13	96	218

				L							I
157	153	174	168	150	152	129	151	172	161	155	156
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187	196	235	75	1	81	47	0	6	217	255	211
183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

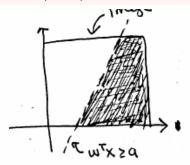
Half Plane Tester

The half plane tester problem is, given an image, return "YES" if the image is a half plane, and "NO" otherwise.



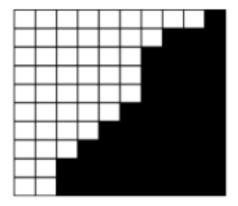
Half Plane Tester

An image is a half plane if there exists a $w \in \mathbb{R}^2$ and an $a \in \mathbb{R}$ such that pixel x is black (white) if and only if $w^T x \ge a$.



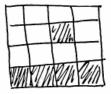
Half Plane Tester

The ϵ -tester version of the half plane tester problem is, given an image, return "YES" if the image is a half plane, and if the image is ϵ -far from being a half plane return "NO" with probability at least p.

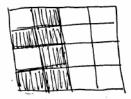


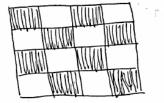
$\epsilon\text{-}\mathsf{far}$ from a half plane

What is the ϵ in the examples below?





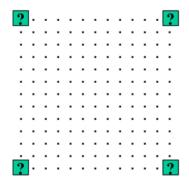




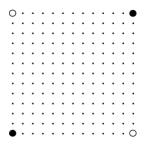
$\epsilon\text{-tester}$ for Half Plane

- ▷ Step 1: Determine what type of half plane this could be
- ▷ Step 2: Use random sampling in order to confirm, or reject

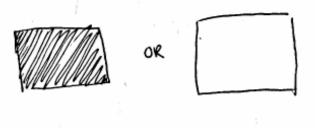
Step 1: Look at the four sides of the image, count how many have different color endpoints.



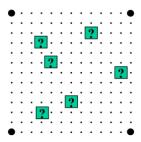
Case 1: All four sides have different color endpoint \implies return "NO"



Case 2: No sides have different color endpoints



Do random sampling to decide with high probability if all one color



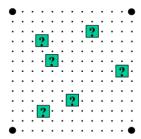
Witness Lemma

If a test catches a witness with probability $\geq \epsilon$, then

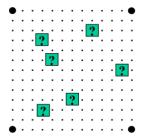
$$s = \frac{\ln\left(\frac{1}{1-p}\right)}{\epsilon}$$

iterations of the test catches a witness with probability $\geq p$.

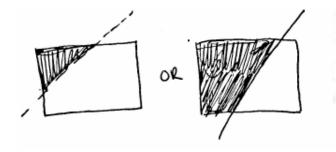
If ϵ -far from half plane \implies all black (white) but with ϵ fraction of white (black) pixels.



Take $s = \ln\left(\frac{1}{1-p}\right)/\epsilon$ random samples. If all black/white \implies return "YES". Otherwise \implies return "NO".

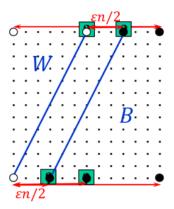


Case 3: Two sides have different color endpoints.



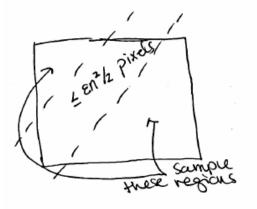
Case 3 of Algorithm

First, do a binary search of those sides to find approximately where the flip occurs.



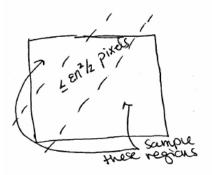
Case 3 of Algorithm

Then sample on either side of the region to test if each side is one color.



Case 3 of Algorithm

The border region contains at most $\epsilon n^2/2$ pixels, therefore if a picture is ϵ far from a half plane there has to be at least $\epsilon n^2/2$ "wrong" pixels in the sampled regions. So the probability of witnessing one is at least $\epsilon/2$.



Analysis of ϵ -tester for Half Plane

- \triangleright If half plane \implies always returns "YES"
- ▷ If ϵ -far from half plane \implies returns "NO" with probability $\ge p$
- \triangleright Run time is looks at $O(\ln(1/\epsilon) + \ln(1/(1-p))/\epsilon)$ pixels

Is the image a convex shape? Is the image a connected shape?

Raskhodnikova, Sofya. "Approximate testing of visual properties." International Workshop on Randomization and Approximation Techniques in Computer Science. Berlin, Heidelberg: Springer Berlin Heidelberg, 2003.



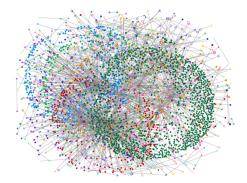
Input x is ϵ -far from property P if ϵ fraction of x has to be changed in order for x to have property P. E.g. P is whether x is an all "0" string.

An algorithm with parameters $\epsilon, p \in (0.1)$, is an ϵ -tester of property *P* if:

- \triangleright If input x has property P it returns "YES" with probability at least p
- ▷ If input x is ϵ -far from property P it returns "NO" with probability at least p.

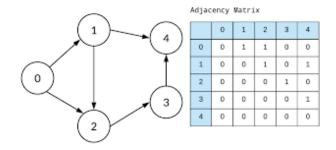
Large Graph

Consider algorithms run on large input undirected graph G = (V, E), where V are n vertices and E are pairs of vertices representing an edge.



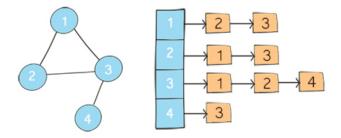
Adjacency Matrix Representation

G = (V, E) can be represented as an adjacency matrix. If |V| = n, then the size of the adjacency matrix is n^2 entries. Good for dense graphs, wasteful for sparse graphs.



Adjacency List Representation

G = (V, E) can be represented as an adjacency list. Good for sparse graphs. If G has bounded degree d, adjacency list is of size nd entries.



The degree of a node if the number of edges incident with it. A graph has bounded degree d if no node in its graph has degree more than d.

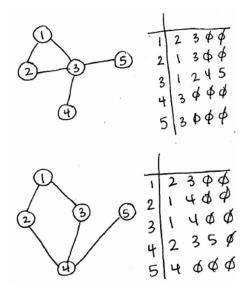
Adjacency List Distance

Let $G_1 = (V, E_1)$ and $G_2 = (V, E_2)$ be graphs of bounded degree d, and |V| = n. Then the distance between G_1 and G_2 is

entries in adjacency lists that are different

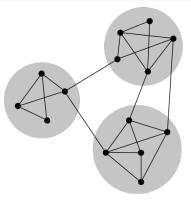
dn

Example of Distance Between Adjacency Lists



Connected Graph

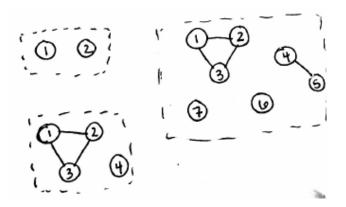
A graph G = (V, E) is connected if for every $u, v \in V$ there exists a path from u to v in G.



Consider only graphs of bounded degree *d*. Graph G = (V, E) is ϵ -far from connected if ϵ fraction of the adjacency list has to be changed in order for *G* to be a connected graph.

$\epsilon\text{-}\mathsf{far}$ from Connected

Let d = 3.



Want algorithm with parameters $\epsilon, p \in (0.1)$, that takes in any graph G = (V, E) of bounded degree d, and:

- ▷ If *G* is connected it returns "YES";
- ▷ If G is ϵ -far from connected it returns "NO" with probability at least p.

- Step 1: Randomly sample some number of nodes
- Step 2: Do a small breadth first search to see if we are in a small, connected component of the graph that is disconnected from the rest of the graph.
- Step 3: If we detect any disconnected component, return "NO". Otherwise, return "YES".

Algorithm

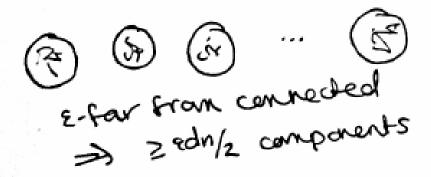
Intuitively, ϵ -far from connected \iff Many connected components that are not connected from the rest of the graph \iff Each of those components is small



Connected Component Lemma

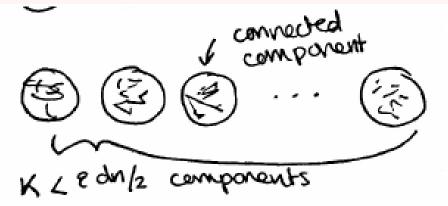
Lemma

If graph G = (V, E) is ϵ -far from connected, then G has at least $\epsilon dn/2$ connected components that are not connected to each other.



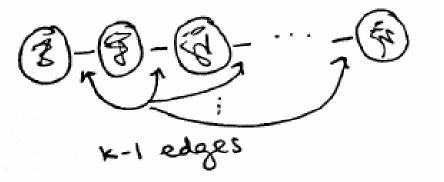
Connected Component Lemma

Proof by the contrapositive. Suppose that *G* has less than $\epsilon dn/2$ connected components that are not connected to each other. Let *k* be the number of such components in *G*.



Connected Component Lemma

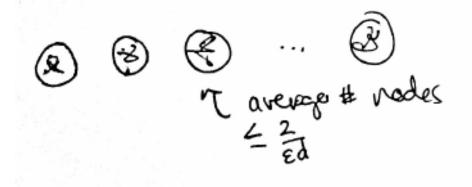
Then it is possible to connect these components with no more than k-1 edges, and therefore we can change the adjacency matrix representation of G in at most $2k < \epsilon dn$ spots and make G connected. Therefore G is less than ϵ -far from connected. \Box



Average Number of Nodes in a Component

Lemma

If graph G = (V, E) is ϵ -far from connected, then G has an average of $2/(\epsilon d)$ nodes in each of its at least $\epsilon dn/2$ components.



Average Number of Nodes in a Component

Proof.

From the previous Lemma, G has at least $\epsilon dn/2$ components. Therefore the average number of nodes is at most

$$\frac{n}{\epsilon dn/2} = \frac{2}{\epsilon d}.$$

Theorem (Markov's Inequality)

Let X be a non-negative random variable, and let a > 0. Then

$$P(X \ge a\mathbb{E}(X)) \le rac{1}{a}.$$

Number of Small Components

Lemma

If G is ϵ -far from connected it has at least $\epsilon dn/4$ connected components of size at most $4/(\epsilon d)$.

Proof.

Suppose we uniformly randomly choose a component of G, and let the random variable X be the number of nodes in this connected component. Then by applying Markov's and the previous lemma, we have that

$$P(X \ge 2\mathbb{E}[X]) \le \frac{1}{2}.$$

Therefore at least half of G's components have the number of nodes at most $4/(\epsilon d)$.

Probability of Finding a Small Component

Since each small connected component has at least a single element in it, this means that if we uniformly randomly sample an element then we have at least a $\epsilon d/4$ chance of being in a small component!

Witness Lemma

If a test catches a witness with probability $\geq \epsilon$, then

$$s = \frac{\ln\left(\frac{1}{1-p}\right)}{\epsilon}$$

iterations of the test catches a witness with probability $\geq p$.

- ▷ Step 1: Randomly sample $s = 4 \ln(1/(1-p))/(\epsilon d)$ number of nodes
- ▷ Step 2: Do a breadth first search of size at most $4/(\epsilon d)$ for each of the nodes.
- \triangleright Step 3: If we detect any disconnected component, return "NO". Otherwise, return "YES".